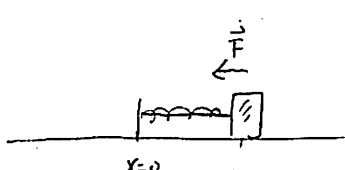
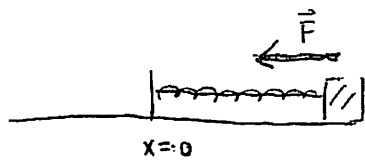


§ restoring force

if our restoring force is $F = -k \Delta x$
 ie  Δx displacement
 minus sign means opposite direction

for simplicity
 we usually write it as
 $F = -kx$ or $\vec{F} = -k\vec{x}$



more further from equilibrium point,
 the restoring force is bigger

$\vec{F} = -k\vec{x}$, for spring, we call it Hooke's law

§ equation of motion

by Newton 2nd law: $\vec{F} = m\vec{a}$, now $\vec{F} = -k\vec{x}$

hence $\vec{F} = m\vec{a} = -k\vec{x}$

for convenience, we deal 1D case, so we drop $\vec{}$ = vector sign.

instead, we use + to mean $+\hat{x}$, - to mean $-\hat{x}$

$F = ma = -kx$

displacement from equilibrium; more rigor, we should write it as Δx

$$ma = -kx$$

↑ acceleration

----- derivation with some calculus -----

Ps. from calculus:

$$a = \frac{d^2x}{dt^2} \equiv \ddot{x} \quad \dots \text{just notation}$$

$$m \ddot{x} + kx = 0$$

$$\ddot{x} + \frac{k}{m}x = 0$$

we define $\frac{k}{m} = \omega^2$

$$\ddot{x} + \omega^2 x = 0, \text{ the solution is } x(t) = \underbrace{C_1}_{\uparrow} \cdot \sin(\omega t) + \underbrace{C_2}_{\uparrow} \cdot \cos(\omega t)$$

need initial condition
to determine C_1, C_2 const.

ω is angular frequency; how much radius per time

$$\omega = \frac{2\pi}{T} = \frac{1 \text{ circle} = 2\pi \text{ radius}}{1 \text{ circle take } T \text{ sec}}$$

$$\omega = \frac{2\pi}{T} = \sqrt{\frac{k}{m}}$$

ie. time $t=0$, we have no displacement

↙

$$\underline{T = 2\pi \sqrt{\frac{m}{k}}}, \text{ and } \underline{X(t) = A \sin(\omega t)}$$

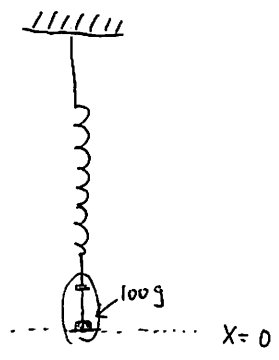
Part 1

in this experiment, we use spring to oscillate vertically.

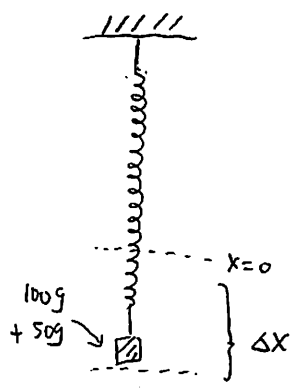
initially, we hang total 100g at the end of spring

- /
- weight hanger 50g
- + mass 50g

and set the position is our equilibrium point
(reference point)



then add mass, to measure displacement



added mass	Δx
50g	5cm
100g	10cm
⋮	⋮

key in your data into template SHM

to check $|F| = k|\Delta x|$; Hooke's law

Part 2

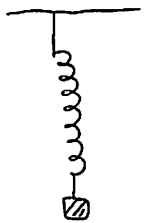
$$T = 2\pi \sqrt{\frac{m}{k}}$$

↑
period
of one oscillation

← mass

← spring const

However, when we let spring oscillate vertically,



we should account the effective mass of spring

m_s = the mass of spring

m_s^* = the effective mass of spring

they have this relation $m_s^* = \frac{1}{3} m_s$

So.

$$T = 2\pi \sqrt{\frac{m + m_s^*}{k}}$$

↑ the total mass you hang

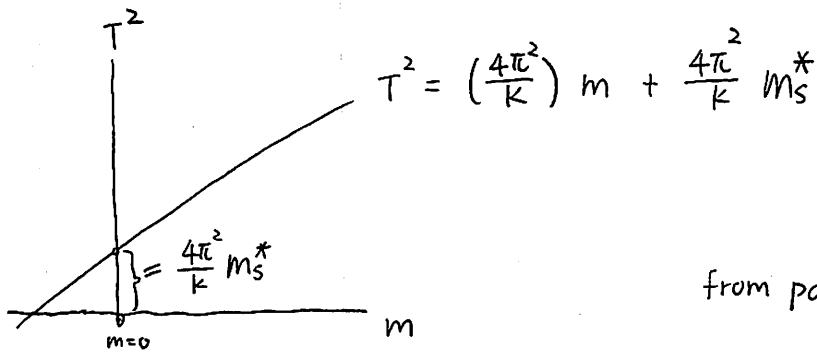
← the effective mass of spring

do some manipulation:

$$T^2 = \frac{4\pi^2}{k} (m + m_s^*)$$

$$T^2 = \frac{4\pi^2}{k} m + \frac{4\pi^2}{k} m_s^*$$

in part 2. we plot



from part 1, we know the k

so from the line equation, we can determine m_s^*

our goal is to check

$$\frac{m_s^*}{m_s} \approx \frac{1}{3}$$

we oscillate 20 times to record the period

(mass + hanger) total mass	1 try	2 try	avg.
150g	17.86 sec	18.18 sec	18.02 sec
200g	19.63	19.96	19.79
250	21.77	21.37	21.57
300	23.76	23.25	23.505
350	25.04	24.70	24.87

from plot, we get

$$T^2 = 3.742 m + \underline{0.2408} ;$$

$$\text{by } \frac{4\pi^2}{k} m_s^* = 0.2408 \quad , \quad \text{and } k = 9.314 \text{ from part 1}$$

$$m_s^* = \frac{k}{4\pi^2} \cdot 0.2408$$

$$\cong 0.056 \text{ (kg)}$$

$$m_s^* = 56 \text{ g}$$

our spring mass m_s is 174.2 g

$$\text{so } \frac{m_s^*}{m_s} \cong \frac{56}{174.2} \cong \underline{\underline{0.32}} \quad \text{very near to } \frac{1}{3}$$

Part 1

Simple Harmonic Motion

Name: Hussein Pei-laun
 Lab Partner:
 Date: 03/18/2011

Part 1 - Hooke's Law

No	mass m _a (kg)	Force (N)	Displacement (m)	Best Fit Force (N)	Fit Error
1	0.050	0.490	0.050	0.504	-0.0142
2	0.100	0.980	0.100	0.970	0.0101
3	0.150	1.470	0.150	1.436	0.0344
4	0.200	1.960	0.210	1.994	-0.0344
5	0.250	2.450	0.260	2.460	-0.0101
6	0.300	2.940	0.310	2.926	0.0142

SUMMARY OUTPUT

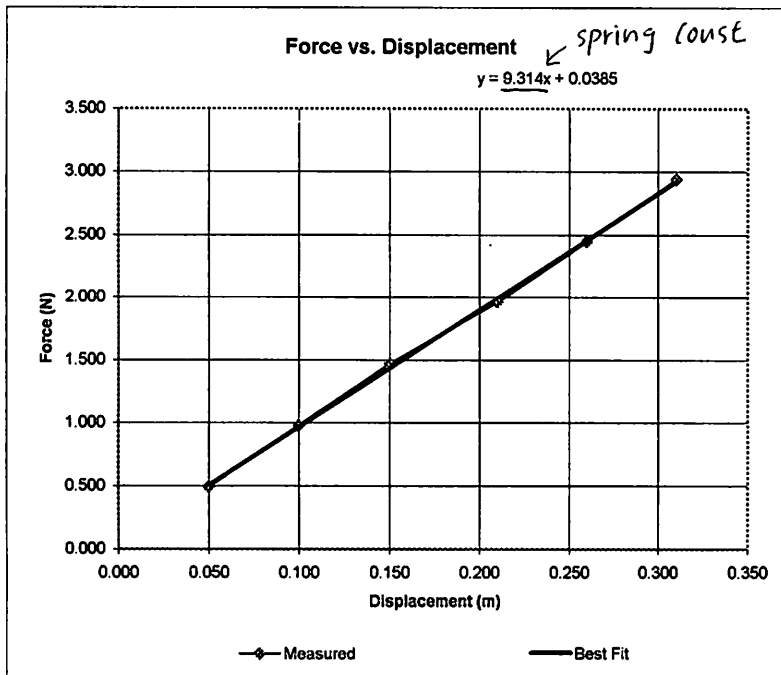
Regression Statistics	
Multiple R	0.999645746
R Square	0.999291617
Adjusted R Square	0.999114522
Standard Error	0.027278408
Observations	6

ANOVA					
	df	SS	MS	F	Significance F
Regression	1	4.198773554	4.198773554	5642.666667	1.88222E-07
Residual	4	0.002976446	0.000744112		
Total	5	4.20175			

	Coefficients	Standard Error	t Stat	P-value	Lower 95%	Upper 95%
Intercept	0.038471074	0.024942792	1.542372421	0.197847522	-0.030781218	0.10772337
X Variable 1	9.314049587	0.123992766	75.11768545	1.88222E-07	8.969790479	9.65830869

RESIDUAL OUTPUT

Observation	Predicted Y	Residuals
1	0.504173554	-0.014173554
2	0.969876033	0.010123967
3	1.435578512	0.034421488
4	1.994421488	-0.034421488
5	2.460123967	-0.010123967
6	2.925826446	0.014173554



$$|F| = k |\Delta x|$$

Part 2

Simple Harmonic Motion

Name: Hussein , Pei-luan
 Lab Partner:
 Date: 03/18/2011

Part 2 - Period² versus Mass

No	Mass m _a (kg)	Time for 20 Oscillations (s)	Period T (s)	Period square T ² (s ²)	Best Fit Period square T ² (s ²)	Fit Error
1	0.150	18.02	0.901	0.812	0.802	0.0097
2	0.200	19.79	0.990	0.979	0.989	-0.0101
3	0.250	21.57	1.079	1.163	1.176	-0.0132
4	0.300	23.505	1.175	1.381	1.363	0.0178
5	0.350	24.87	1.244	1.546	1.551	-0.0042

SUMMARY OUTPUT

Regression Statistics	
Multiple R	0.9989968
R Square	0.9979946
Adjusted R Square	0.9973261
Standard Error	0.0153134
Observations	5

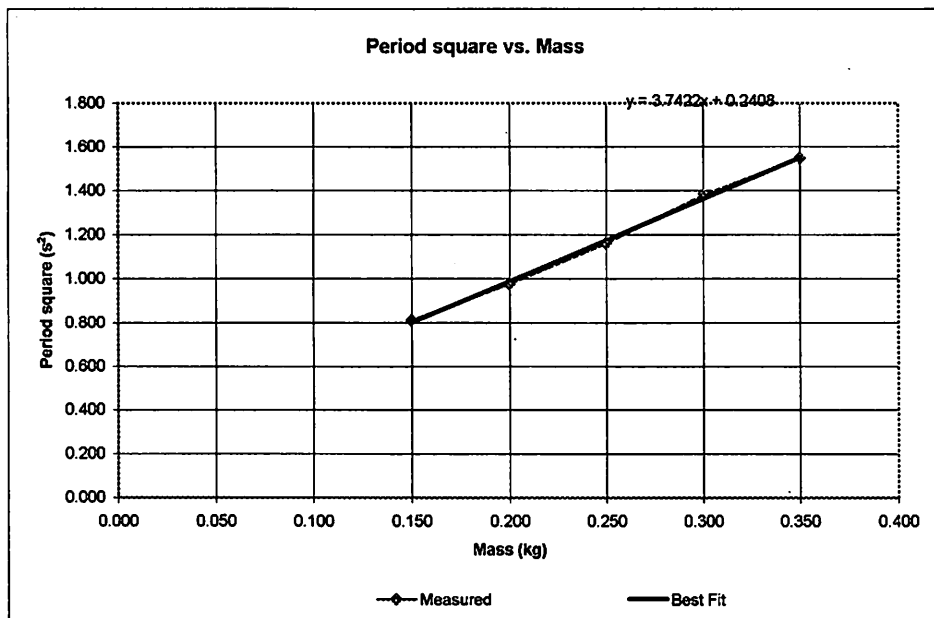
ANOVA

	df	SS	MS	F	Significance F
Regression	1	0.350095838	0.350095838	1492.938515	3.81383E-05
Residual	3	0.000703504	0.000234501		
Total	4	0.350799341			

	Coefficients	Standard Error	t Stat	P-value	Lower 95%	Upper 95%
Intercept	0.2407733	0.025162535	9.568720115	0.002421541	0.160694839	0.3208517
X Variable 1	3.7421696	0.096850643	38.63856254	3.81383E-05	3.433947654	4.0503916

RESIDUAL OUTPUT

Observation	Predicted Y	Residuals
1	0.8020987	0.0097023
2	0.9892072	-0.010096931
3	1.1763157	-0.013153412
4	1.3634241	0.017788419
5	1.5505326	-0.004240375



$$T^2 = \frac{4\pi^2}{k} m + \frac{4\pi^2}{k} m_s^*$$

Questions:

(1) discuss what happens to the period T , if we consider the air drag.
explain your ideas. how much it will change?

(2) the amplitude will affect period T or not??

(of course you can consider the factor of air drag)
explain your ideas

(3) if we do the same experiment in the moon. \Leftarrow (optional problem)

T changes or not?

explain your ideas.